All models are good, but only some are useful



On models



Essentially, all models are wrong, but some are useful.

Box, George E. P.; Norman R. Draper (1987). Empirical Model-Building and Response Surfaces, p. 424, Wiley.







On data and models









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$$F_{ST} = \frac{\sigma^2(p)}{p(1-p)} \simeq \frac{H_T - \overline{H}_S}{H_T}$$
$$F_{ST} \approx \frac{1}{4Nm+1}$$





$$F_{ST} = \frac{\sigma^2(p)}{p(1-p)} = 0.25$$
$$Nm \approx \frac{1}{4} \left(\frac{1}{F_{ST}} - 1\right) \approx 0.76$$



. . . .



$$F_{ST} = \frac{\sigma^2(p)}{p(1-p)} = 0.95$$
$$Nm \approx \frac{1}{4} \left(\frac{1}{F_{ST}} - 1\right) \approx 0.01$$

Population genetics models



Population genetics models













Model comparison
Several tests that establish whether two locations belong to the same population exist. The test by Hudson and Kaplan (1995) seemed particularly powerful even with a single locus.
These days researchers mostly use the program STRUCTURE to establish the number of populations.
A procedure that not only can handle panmixia versus all other gene flow models would help.
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Model comparison
With a criterium such as likelihood we can compare nested models. Commonly we use a likelihood ratio test (LRT) or Akaike's information criterion (AIC) to establish whether phylogenetic trees are statistically different or mutation models have an effect on the outcome, etc.
Kass and Raftery (1995) popularized the Bayes Factor as a Bayesian alternative to the LRT.
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Bayes factor

Theoretically, we can calculate the posterior probability density of the model $1 \ \mbox{and} \ \mbox{model} \ 2$

$$\begin{split} p(M_1|X) &= \frac{p(M_1)p(X|M_1)}{p(X)} \\ p(M_2|X) &= \frac{p(M_2)p(X|M_1)}{p(X)} \end{split}$$

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Bayes factor

Theoretically, we can calculate the posterior probability density of the model $1 \ \mbox{and} \ \mbox{model} \ 2$

$$\frac{p(M_1|X)}{p(M_2|X)} = \frac{\frac{p(M_1)p(X|M_1)}{p(X)}}{\frac{p(M_2)p(X|M_1)}{p(X)}}$$





We could look at the posterior odds ratio or equivalently the Bayes factors.

$$\frac{p(M_1|X)}{p(M_2|X)} = \frac{p(M_1)}{p(M_2)} \times \frac{p(X|M_1)}{p(X|M_2)}$$

 $BF = \frac{p(X|M_1)}{p(X|M_2)} \qquad LBF = 2\ln BF = 2\ln \left(\frac{p(X|M_1)}{p(X|M_2)}\right)$

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Bayes factor

 $BF = \frac{p(X|M_1)}{p(X|M_2)} \qquad LBF = 2\ln BF = 2\ln \left(\frac{p(X|M_1)}{p(X|M_2)}\right)$

The magnitude of BF gives us evidence against or for hypothesis M_2

$$LBF = 2 \ln BF = z \quad \begin{cases} 0 < |z| < 2 & \text{No real difference} \\ 2 < |z| < 6 & \text{Positive} \\ 6 < |z| < 10 & \text{Strong} \\ |z| > 10 & \text{Very strong} \end{cases}$$

Bayes factor example



LBF =
$$2\ln BF = 2\ln \left(\frac{p(X|M_1)}{p(X|M_2)}\right) = 2(-9638.69) - (-9641.01) = 4.64$$

The magnitude of BF gives us evidence against or for hypothesis M_2

$$\label{eq:LBF} \mathrm{LBF} = 2\ln\mathrm{BF} = z \quad \begin{cases} 0 < |z| < 2 & \text{No real difference} \\ 2 < |z| < 6 & \text{Positive} \\ 6 < |z| < 10 & \text{Strong} \\ |z| > 10 & \text{Very strong} \end{cases}$$

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Posterior model probability

Instead of calculating the Bayes factor we could use the probability of all tested models M_i and use them as weights (cf. Burnham and Anderson, 1998)

$$p_i^* = \frac{p(X|M_i)}{\sum_j p(X|M_j)}, \qquad \sum_i p_i^* = 1, \qquad \ell_1 = -9638.61, \quad \ell_2 = -9641.01$$
$$p_1^* = \frac{\exp(\ell_1)}{\exp(\ell_1) + \exp(\ell_2)} = 0.911$$
$$p_2^* = \frac{\exp(\ell_2)}{\exp(\ell_1) + \exp(\ell_2)} = 0.089$$

(example continued)





Marginal likelihood

Typically, it is rather difficult to calculate the marginal likelihoods with good accuracy, because most often we only approximate the posterior distribution using Markov chain Monte Carlo (MCMC).

In MCMC we need to know only differences and therefore we typically do not need to calculate the denominator to calculate the Posterior distribution $p(\Theta|X)$:

$$p(\Theta|X,M) = \frac{p(\Theta)p(X|\Theta)}{p(X|M)} = \frac{p(\Theta)p(X|\Theta)}{\int_{\Theta} p(\Theta)p(X|\Theta)d\Theta}$$

where p(X|M) is the marginal likelihood, which we need for our model selection!



Simulated data

Two loci simulated from model xODx:

Model	Log(mL)	LBF*	Model-probability
1: xxxx:	-9662.42	-23.73	0.0000
2: xDxx:	-9661.98	-23.29	0.0000
3: xxDx:	-9661.52	-22.83	0.0000
4: xd0x:	-9656.51	-17.82	0.0000
5: xDOx:	-9649.33	-10.64	0.0000
6: xx0x:	-9648.93	-10.24	0.0000
7: x0dx:	-9641.77	-3.08	0.0402
8: x0xx:	-9641.01	-2.32	0.0859
9: xODx:	-9638.69	0.00	0.8739

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Simulated data





Lisa N. Barrow, A. T. Bigelow, C. A. Phillips, and E. Moriarty Lemmon (2015) Phylogeographic inference using Bayesian model comparison across a fragmented chorus frog species complex. Molecular Ecology Best Model in Migrate-n (ILLN) TEX refugium, 2 routes, 5 pops N Model Probability = 0.99977 Θ.,, Θ_{CGP} = 0.067 1.0 (CGP) ARV . = 0 0 0.633 TEX Θ-69.8



A real example

Frog picture: http://mdc.mo.gov/discover-nature/field-guide

Population splitting model



The relationship among individuals can be expressed, looking backward in time, by a waiting process where random lineages

coalesce

migrate between populations

split off an ancestral population

Each of these processes can be expressed as a waiting time process with rate λ for Npopulations and k_j lineages in population j.



Each of these processes can be expressed as a waiting time process with rate λ for *N* populations and k_j lineages in population *j*:

$$\begin{split} \lambda_{\text{two lineages coalesce}} &= \sum_{j=1}^{N} \frac{k_j (k_j - 1)}{4N} \\ \lambda_{\text{lineages migrate}} &= \sum_{j=1}^{N} \sum_{i=1, i \neq j}^{N} k_j m_{ij} \\ \lambda_{\text{a lineage splits off}^*} &= \frac{\sqrt{\frac{2}{\pi}} e^{\frac{(t-\mu)^2}{2b^2}}}{b\left(1 - \operatorname{erf}\left(\frac{t-\mu}{\sqrt{2b}}\right)\right)} \end{split}$$

*using a Normal distribution to model the splitting time between two populations.

Combining the parts

$$P(\Theta|\mathbf{D}_{1}, \mathbf{D}_{2}, ..., \mu) = \frac{P(\Theta)P(\mathbf{D}_{1}, \mathbf{D}_{2}, ...|\Theta)}{P(\mathbf{D}_{1}, \mathbf{D}_{2}, ...)} = \frac{P(\Theta)\int_{G}P(G|\Theta)\prod_{i}^{n_{\text{Loci}}}P(\mathbf{D}_{i}|\Theta, \mu)dG}{\int_{\Theta}P(\Theta)\int_{G}P(G|\Theta)\prod_{i}^{n_{\text{Loci}}}P(\mathbf{D}_{i}|\Theta, \mu)dGd\Theta}$$

$$P(G|\Theta) = \prod_{i=1}^{K} \lambda_{x} \exp(-t_{i}[\lambda_{\text{coalescence}} + \lambda_{\text{migration}} + \lambda_{\text{splitting}}])$$

$$\Theta \qquad \text{vector of parameters for population size, migration and splitting parameters.}$$

$$\mathbf{D}_{1}, \mathbf{D}_{2}, ... \qquad \text{independent genetic sequence data,}$$

$$\mu \qquad \text{mutation model,}$$

$$G \qquad \text{nuisance genealogies that we integrate out (we are interested in the parameters not the trees).}$$

- the particular event on the genealogy number of total events on the genealogy $x \\ K$











You may be surprised that your favored model does not win in a model comparison competition, but figuring out the model order leads oftentimes to new insights about the problem.

Models by themselves are not true or wrong. BUT they may not fit your data well, OR they describe your data even when you "know" that the model is insufficient.

